

DFS60B-THPA10000

DFS60

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DFS60B-THPA10000	1036911

Other models and accessories → www.sick.com/DFS60

Illustration may differ



Detailed technical data

Performance

Pulses per revolution	10,000 ¹⁾ 10,000
Measuring step	90° / electronically/ppr
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°
Initialization time	32 ms ²⁾ 30 ms

 $^{^{1)}}$, see maximum revolution range.

Electrical data

Electrical interface	4.5 V 32 V, TTL/HTL programmable
Initialisation time after power on	32 ms ¹⁾ 30 ms
Connection type	Male connector, 12-pin, radial, M23
Power consumption max. without load	0.7 W (without load)
Load current max.	≤ 30 mA
Maximum output frequency	600 kHz
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ^{2) 3)}
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) ⁴⁾

¹⁾ With mechanical zero pulse width.

²⁾ With mechanical zero pulse width.

 $^{^{2)}}$ Programming TTL with \geq 5,5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{^{3)}}$ Programming HTL or TTL with < 5,5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

⁴⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Shaft diameter	15 mm
Mass	0.2 kg
Shaft material	Metal
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.2 mm
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.1 mm
Maximum operating speed	6,000 min ⁻¹ 1)
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10^10 revolutions
Max. angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (according to IEC 60529) ¹⁾ IP65, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Working temperature range	-40 °C +100 °C ²⁾ -30 °C +100 °C ³⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	70 g (according to EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)

¹⁾ With mating connector fitted.

Classifications

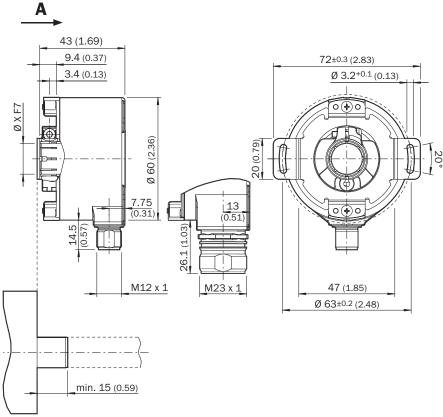
ECI@ss 5.0	27270501
ECI@ss 5.1.4	27270501
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270501
ECI@ss 8.0	27270501
ECI@ss 8.1	27270501
ECI@ss 9.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

²⁾ Stationary position of the cable.

³⁾ Flexible position of the cable.

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, radial connector outlet M12 and M23

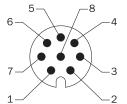


General tolerances according to DIN ISO 2768-mk
① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder



View of M23 male device connector on encoder

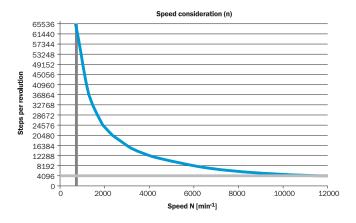


PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V _{ss}	Explanation
1	6	Brown	_A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	В	SIN-	Signal wire
4	8	Pink	В	SIN+	Signal wire
5	4	Yellow	_Z	_Z	Signal wire
6	3	Violet	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection of the encoder
8	12	Red	+U _s	+U _s	Supply voltage (volt-free to housing)
-	9	-	n.c.	n.c.	Not assigned
-	2	-	n.c.	n.c.	Not assigned
-	11	-	n.c.	n.c.	Not assigned
-	7 1)	-	O-SET 1)	n.c.	Set zero pulse 1)
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

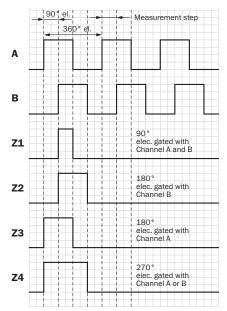
¹⁾ For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_s for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

Diagram

Maximum revolution range

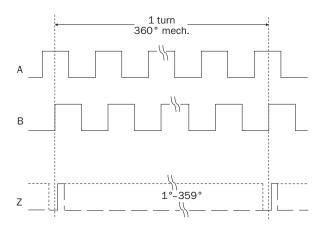


Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Recommended accessories

Other models and accessories → www.sick.com/DFS60

	Brief description	Туре	Part no.
Plug connecto	ors and cables		
	Head A: female connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-G	6027538
(F)	Head A: female connector, M23, 12-pin, angled Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-W01	2072580

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	Brief description	Туре	Part no.		
	Head A: male connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE®, SSI, Incremental, RS-422, shielded	STE-2312-G	6027537		
Programming and configuration tools					
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616		
A	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254		

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